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## On a family of Riemannian manifolds defined on an $m$ -disk

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## ON A FAMILY OF RIEMANNIAN MANIFOLDS DEFINED ON AN $m$ -DISK

Dedicated to Professor MASARU OSIMA on his 60th birthday

TOMINOSUKE OTSUKI

### 1. The Riemannian manifold $O_n^m$

Let  $R^m$  be the  $m$ -dimensional coordinate space with the canonical coordinates  $u_1, u_2, \dots, u_m$  and  $D^m$  be the unit  $m$ -disk

$$(u, u) = \sum_i u_i u_i < 1,$$

where  $u = (u_1, \dots, u_m)$ . We denote the Riemannian manifold defined on  $D^m$  with the following metric :

$$(1.1) \quad ds^2 = (1 - \sum_i u_i u_i)^{n-2} \{ \sum_i du_i du_i - \sum_{i < j} (u_i du_j - u_j du_i)^2 \}$$

by  $O_n^m$ , where  $n$  is a real constant.

In order to give a meaning of (1.1), suppose that  $n$  is an integer  $\geq 2$  and consider the unit  $(n+m-1)$ -sphere  $S^{n+m-1} \subset R^{n+m}$  given by  $\sum_{i=1}^{n+m} u_i u_i = 1$ . Let us consider as

$$R^{n+m} = R^n \times R^m$$

and take a smooth curve  $C$  in  $D^m$ . Then, for  $C$  we construct an  $n$ -dimensional submanifold  $M^n(C)$  in  $S^{n+m-1}$  as follows :

$$(1.2) \quad M^n(C) = \{ \cup S^{n-1}(\rho) \times u, u \in C \},$$

where

$$(1.3) \quad \rho = \rho(u) = \sqrt{1 - \sum_{i=1}^m u_i u_i}$$

and  $S^{n-1}(\rho)$  is the  $(n-1)$ -sphere of radius  $\rho$  about the origin of  $R^n$ .

The  $n$ -dimensional volume of  $M^n(C)$  is clearly given by the formula :

$$(1.4) \quad V(M^n(C)) = c_{n-1} \int_C \rho^{n-1} \sqrt{d\rho d\rho + (du, du)},$$

where  $c_{n-1}$  is the volume of the unit  $(n-1)$ -sphere  $S^{n-1}$ , i. e.

$$c_{n-1} = 2\pi^{n/2} / \Gamma(n/2).$$

**Lemma 1.** *The metric (1.1) can be written as*

$$ds^2 = \rho^{2(n-1)} \{d\rho d\rho + (du, du)\}.$$

*Proof.* From  $\rho^2 = 1 - (u, u)$ , we have  $\rho d\rho = -(u, du)$ . Hence

$$\begin{aligned} \rho^{2(n-1)} \{d\rho d\rho + (du, du)\} &= \rho^{2(n-1)} \left\{ \frac{(u, du)^2}{\rho^2} + (du, du) \right\} \\ &= \rho^{2(n-2)} \{(u, du)^2 + (1 - (u, u)) (du, du)\} \\ &= \rho^{2(n-2)} \{(du, du) - ((u, u)(du, du) - (u, du)^2)\} \\ &= (1 - \sum_i u_i u_i)^{n-2} \left\{ \sum_i du_i du_i - \sum_{i < j} (u_i du_j - u_j du_i)^2 \right\} \end{aligned}$$

Q. E. D.

Lemma 1 and (1.4) imply immediately the following

**Lemma 2.** *An extremal of the volume of the family of the submanifolds  $\{M^n(C); C \text{ is a smooth curve in } D^m\}$  in the  $(n+m-1)$ -sphere corresponds to a geodesic of  $O_n^m$  and vice versa.*

**Remark.** In the definition of  $O_n^m$ , we consider  $n$  as a real number. Especially, the cases of  $n=1, 0$ , have the following meanings:

$O_1^m$  is the representation of the north hemisphere of  $S^m$  through the orthogonal projection onto the equatorial hyperplane of  $R^{m+1} (\supset S^m)$ .

$O_0^m$  is the Cayley-Klein representation of the hyperbolic  $m$ -space of curvature 1. In fact, for any two points  $u, v = u + du$  in  $D^m$ , let  $p, q$  be the points of intersection of the straight line joining  $u$  and  $v$  and the unit  $(m-1)$ -sphere  $S^{m-1} = \partial D^m$ . Denoting  $p$  and  $q$  in the form  $(1-\lambda)u + \lambda v$ , we have easily

$$(du, du) \lambda^2 + 2(u, du) \lambda - \rho^2 = 0,$$

hence

$$\lambda = \frac{-(u, du) \pm \delta_i}{(du, du)} = \lambda_{\pm},$$

where

$$\delta_i^2 = (du, du) - \sum_{i < j} (u_i du_j - u_j du_i)^2.$$

Thus, we have the cross ratio of the four points  $u, v, p, q$ :

$$R(u, v : p, q) = \frac{\lambda_+}{1 - \lambda_+} \cdot \frac{1 - \lambda_-}{\lambda_-} = \frac{\rho^2 - (u, du) + \delta_s}{\rho^2 - (u, du) - \delta_s},$$

from which

$$\begin{aligned} \log R(u, v : p, q) &= \log \left( 1 - \frac{(u, du) - \delta_s}{\rho^2} \right) - \log \left( 1 - \frac{(u, du) + \delta_s}{\rho^2} \right) \\ &= \frac{2\delta_s}{\rho^2} + [2], \end{aligned}$$

where  $[2]$  denotes the part of higher order of  $du$ , when we regard  $du$  as infinitesimal. Therefore, the Riemannian metric of the hyperbolic  $m$ -space  $H^m$  in this representation can be written as

$$ds^2 = \frac{a\delta_s^2}{\rho^4} = a(1 - (u, u))^{-2} \{ (du, du) - \sum_{i,j} (u_i du_j - u_j du_i)^2 \},$$

where  $a$  is a constant.

## 2. Geodesics of $O_n^m$

We shall investigate the geodesics of  $O_n^m$ .

From (1.1), the components of the metric tensor of  $O_n^m$  are

$$(2.1) \quad g_{ij} = \rho^{2n-4} (\rho^2 \delta_{ij} + u_i u_j)$$

and

$$(2.2) \quad g^{ij} = \rho^{-2n+2} (\delta^{ij} - u^i u^j),$$

where  $\delta_{ij}$  are the Kronecker's  $\delta$  and  $u^i = u_i$ . From (2.1), we have

$$\frac{\partial g_{ij}}{\partial u^k} = \rho^{2n-6} \{ \rho^2 (u_i \delta_{jk} + u_j \delta_{ik}) - 2(n-1) \rho^2 u_k \delta_{ij} - 2(n-2) u_i u_j u_k \}$$

and

$$\begin{aligned} (2.3) \quad [ij, k] &= \frac{1}{2} \left\{ \frac{\partial g_{jk}}{\partial u^i} + \frac{\partial g_{ik}}{\partial u^j} - \frac{\partial g_{ij}}{\partial u^k} \right\} \\ &= \rho^{2n-6} [ \rho^2 \{ n u_k \delta_{ij} - (n-1) (u_i \delta_{jk} + u_j \delta_{ik}) \} \\ &\quad - (n-2) u_i u_j u_k ]. \end{aligned}$$

Thus, using the Einstein convention, the Christoffel's symbols of  $O_n^m$  in the coordinates  $u^i$  are given by

$$\begin{aligned}
\left\{ \begin{smallmatrix} l \\ ij \end{smallmatrix} \right\} &= g^{ik} [ij, k] \\
&= \rho^{-4} (\delta^{ik} - u^i u^k) [\rho^2 \{ n u_k \delta_{ij} - (n-1)(u_i \delta_{jk} + u_j \delta_{ik}) \} \\
&\quad - (n-2) u_i u_j u_k] \\
&= \rho^{-4} [\rho^2 \{ n u^i \delta_{ij} - (n-1)(u_i \delta_j^i + u_j \delta_i^i) \} - (n-2) u_i u_j u^i \\
&\quad - \rho^2 u^i \{ n(u, u) \delta_{ij} - 2(n-1) u_i u_j \} + (n-2)(u, u) u^i u_i u_j],
\end{aligned}$$

i. e.

$$(2.4) \quad \left\{ \begin{smallmatrix} l \\ ij \end{smallmatrix} \right\} = \frac{1}{\rho^2} [n(\rho^2 \delta_{ij} + u_i u_j) u^l - (n-1)(u_i \delta_j^l + u_j \delta_i^l)].$$

**Theorem 1.** For any  $p$ -dimensional linear space  $E^p$  ( $p < m$ ) through the origin of  $R^m$ ,  $D^m \cap E^p$  is a totally geodesic submanifold of  $O_n^m$ , which is an  $O_n^p$ .

*Proof.* As easily seen by Lemma 1, the metric (1.1) is invariant under the rotations of  $R^m$  about the origin. Hence, we may suppose that  $E^p$  is given by

$$u_{p+1} = u_{p+2} = \cdots = u_m = 0.$$

For any tangent vector fields  $X = \sum_{a=1}^p X^a \partial / \partial u^a$ ,  $Y = \sum_{a=1}^p Y^a \partial / \partial u^a$  of  $E^p \cap D^m$ , we put

$$\nabla_x Y = \sum_{i=1}^m Z^i \partial / \partial u^i,$$

where  $\nabla$  denotes the covariant differentiation of  $O_n^m$  and  $Z^i$  is given by

$$Z^i = \sum_a \frac{\partial Y^i}{\partial u^a} X^a + \sum_{a,b} \left\{ \begin{smallmatrix} i \\ ab \end{smallmatrix} \right\} Y^a X^b.$$

By means of (2.4), on  $E^p \cap D^m$  we have

$$\begin{aligned}
\left\{ \begin{smallmatrix} i \\ ab \end{smallmatrix} \right\} &= -\frac{n-1}{\rho^2} (u_a \delta_b^i + u_b \delta_a^i) = 0 \\
&\text{for } i > p \text{ and } a, b \leq p.
\end{aligned}$$

Hence we have

$$Z^i = 0 \quad \text{for } i > p,$$

that is  $\Delta_x Y$  is also a tangent vector field of  $E^p \cap D^m$ . This shows that

$E^n \cap D^m$  is a totally geodesic submanifold of  $O_n^m$ , which can be considered as an  $O_n^p$  by the induced metric from  $O_n^m$ . Q. E. D.

**Corollary.** *Any geodesic of  $O_n^m$  lies on a plane through the origin of  $R^m$  and can be considered as a geodesic of  $O_n^2$ .*

### 3. Certain properties of $M^n(C)$ in $S^{n+m-1}$

In this section, we suppose that  $n$  is an integer  $\geq 2$ . By means of Lemma 2, an extremal of the volume of the family of the submanifolds  $\{M^n(C)\}$  corresponds to a geodesic of  $O_n^m$  and then  $C$  is also a geodesic of an  $O_n^2 \subset O_n^m$  by Corollary of Theorem 1. Accordingly,  $M^n(C)$  can be considered as

$$M^n(C) \subset S^{n+1} \subset S^{n+m-1}$$

and it belongs to a family of hypersurfaces of  $S^{n+1}$ , which has two principal curvatures with multiplicity 1 and  $n-1$ .

Now, let  $C$  be a smooth curve in  $D^m$  not passing through the origin of  $D^m$  and  $\bar{s}$  be its arclength. We take an orthonormal frame field  $(q, \bar{\xi}_1, \bar{\xi}_2, \dots, \bar{\xi}_m)$  along  $C$  in  $R^m$  such that

$$(3.1) \quad q = f \bar{\xi}_1 - h \bar{\xi}_2 \quad (h \geq 0),$$

where  $q$  also denotes the position vector of the moving point of  $C$  and

$$(3.2) \quad \bar{\xi}_1 = \frac{dq}{d\bar{s}}.$$

If  $q$  is not parallel to  $\bar{\xi}_1$ ,  $\bar{\xi}_2$  is determined uniquely at  $q$ . We have easily

$$(3.3) \quad 1 - \rho^2 = f^2 + h^2,$$

where  $\rho^2 = 1 - (q, q)$  by (1.3). From (3.2) and (3.3) we obtain

$$\rho \frac{d\rho}{d\bar{s}} = - \left( q, \frac{dq}{d\bar{s}} \right) = - (q, \bar{\xi}_1) = -f,$$

hence

$$(3.4) \quad \frac{d\rho}{d\bar{s}} = - \frac{f}{\rho}.$$

We put

$$(3.5) \quad \bar{k}_a = \left( \frac{d\bar{\xi}_2}{d\bar{s}}, \bar{\xi}_a \right), \quad a = 1, 3, \dots, m.$$

Especially we have

$$(3.6) \quad \bar{k}_1 = \left( \frac{d\bar{\xi}_2}{d\bar{s}}, \bar{\xi}_1 \right) = - \left( \frac{d\bar{\xi}_1}{d\bar{s}}, \bar{\xi}_2 \right),$$

which shows that  $-\bar{k}_1 \bar{\xi}_2$  is the orthogonal projection of the principal curvature vector  $\frac{d\bar{\xi}_1}{d\bar{s}}$  of  $C$  onto the plane through the origin of  $D^m$  and the tangent line of  $C$  at  $q$ .

On the other hand, let  $(\bar{e}_1, \dots, \bar{e}_n)$  be the moving orthonormal frame of  $R^n$  at the origin and put

$$(3.7) \quad d\bar{e}_i = \sum_j \omega_{ij} \bar{e}_j, \quad \bar{\omega}_{ij} + \bar{\omega}_{ji} = 0.$$

The generating moving point  $p$  of  $M^n(C)$  is given by

$$(3.8) \quad p = q + \rho \bar{e}_n = \rho \bar{e}_n + f \bar{\xi}_1 - h \bar{\xi}_2,$$

from which we obtain by differentiation

$$dp = \rho \sum_{a=1}^{n-1} \omega_{na} \bar{e}_a + d\bar{s} \left( \frac{d\rho}{d\bar{s}} \bar{e}_n + \bar{\xi}_1 \right).$$

Using (3.3) and (3.4), if we put

$$(3.9) \quad e_a = \bar{e}_a, \quad e_n = \frac{-f \bar{e}_n + \rho \bar{\xi}_1}{\sqrt{1-h^2}},$$

$$\omega_a = \rho \bar{\omega}_{na}, \quad \omega_n = \frac{\sqrt{1-h^2}}{\rho} d\bar{s},$$

then we have the equality

$$dp = \sum_{i=1}^n \omega_i e_i$$

and  $(p, e_1, \dots, e_n)$  is an orthonormal frame of  $M^n(C)$  at  $p$ .

Next, if we put

$$(3.10) \quad e_{n+1} = -\frac{h}{\sqrt{1-h^2}} (\rho \bar{e}_n + f \bar{\xi}_1) - \sqrt{1-h^2} \bar{\xi}_2,$$

then

$$\|e_{n+1}\|^2 = \frac{h^2}{1-h^2}(\rho^2 + f^2) + 1 - h^2 = 1.$$

$e_{n+1}$  is clearly orthogonal to  $e_1, e_2, \dots, e_n$ . Using (3.3) and (3.8), we obtain

$$\begin{aligned} (p, e_{n+1}) &= (\rho \bar{e}_n + f \bar{\xi}_1 - h \bar{\xi}_2, e_{n+1}) \\ &= -\frac{h\rho^2}{\sqrt{1-h^2}} - \frac{hf^2}{\sqrt{1-h^2}} + h\sqrt{1-h^2} = 0, \end{aligned}$$

which shows that  $e_{n+1}$  is also tangent to  $S^{n+m-1}$ .

Furthermore, putting

$$(3.11) \quad e_\lambda = \bar{\xi}_{\lambda-n+1}, \quad \lambda > n+1,$$

we obtain a moving orthonormal frame  $(p, e_1, \dots, e_{n+m-1})$  of  $S_{n+m-1}$  defined along  $M'(C)$ . From this frame, we obtain by the covariant differentiation  $D$  on  $S^{n+m-1}$  the following:

$$\begin{aligned} \omega_{a,n+1} &= (De_a, e_{n+1}) = (d\bar{e}_a, e_{n+1}) \\ &= (d\bar{e}_a, -\frac{h}{\sqrt{1-h^2}}(\rho \bar{e}_n + f \bar{\xi}_1) - \sqrt{1-h^2} \bar{\xi}_2) \\ &= \frac{h\rho \bar{\omega}_{na}}{\sqrt{1-h^2}} = \frac{h}{\sqrt{1-h^2}} \omega_a \quad \text{for } a = 1, 2, \dots, n-1 \end{aligned}$$

and

$$\begin{aligned} \omega_{n,n+1} &= (De_n, e_{n+1}) = (de_n, e_{n+1}) \\ &= \left(d\frac{-f\bar{e}_n + \rho\bar{\xi}_1}{\sqrt{1-h^2}}, e_{n+1}\right) = \frac{1}{\sqrt{1-h^2}}(d(-f\bar{e}_n + \rho\bar{\xi}_1), e_{n+1}). \end{aligned}$$

Since

$$\begin{aligned} -\sqrt{1-h^2}\omega_{n,n+1} &= \left(\left(-\frac{df}{d\bar{s}}\bar{e}_n + \frac{d\rho}{d\bar{s}}\bar{\xi}_1 + \rho\frac{d\bar{\xi}_1}{d\bar{s}}\right)d\bar{s} - f d\bar{e}_n\right. \\ &\quad \left. + \frac{h}{\sqrt{1-h^2}}(\rho\bar{e}_n + f\bar{\xi}_1) + \sqrt{1-h^2}\bar{\xi}_2\right) \\ &= \left\{\frac{h}{\sqrt{1-h^2}}\left(-\rho\frac{df}{d\bar{s}} + f\frac{d\rho}{d\bar{s}}\right) - \rho\sqrt{1-h^2}\bar{k}\right\}d\bar{s}, \end{aligned}$$

using (3.4) and (3.9) we have



$$\omega_{n,n+1} = \left\{ \frac{h}{\sqrt{(1-h^2)^3}} \left( f^2 + \rho^2 \frac{df}{ds} \right) + \frac{\bar{k}_1 \rho^2}{\sqrt{1-h^2}} \right\} \omega_n.$$

On the other hand, from (3. 1), (3. 2) and (3. 6) we obtain

$$\bar{\xi}_1 = \frac{dq}{ds} = \frac{df}{ds} \bar{\xi}_1 + f \frac{d\bar{\xi}_1}{ds} - \frac{dh}{ds} \bar{\xi}_2 - h \frac{d\bar{\xi}_2}{ds},$$

which implies

$$1 = \frac{df}{ds} - h \left( \bar{\xi}_1, \frac{d\bar{\xi}_2}{ds} \right) = \frac{df}{ds} - h \bar{k}_1,$$

i. e.

$$(3. 12) \quad \frac{df}{ds} = 1 + h \bar{k}_1.$$

Taking the inner product of the above equality with  $\bar{\xi}_2$ , we obtain easily

$$0 = f \left( \bar{\xi}_2, \frac{d\bar{\xi}_1}{ds} \right) - \frac{dh}{ds} = -\bar{k}_1 f - \frac{dh}{ds},$$

i. e.

$$(3. 13) \quad \frac{dh}{ds} = -\bar{k}_1 f.$$

We obtain analogously the following :

$$(3. 14) \quad f \left( \frac{d\bar{\xi}_1}{ds}, \bar{\xi}_a \right) = h \bar{k}_a, \quad a = 3, 4, \dots, n-1.$$

Using (3. 12) and (3. 3), we have

$$\frac{h}{\sqrt{(1-h^2)^3}} \left( f^2 + \rho^2 \frac{df}{ds} \right) + \frac{\bar{k}_1 \rho^2}{\sqrt{1-h^2}} = \frac{h}{\sqrt{1-h^2}} + \frac{\bar{k}_1 \rho^2}{\sqrt{(1-h^2)^3}}.$$

Hence, we obtain the following :

$$(3. 15) \quad \begin{cases} \omega_{a,n+1} = \frac{h}{\sqrt{1-h^2}} \omega_a, & a = 1, 2, \dots, n-1; \\ \omega_{n,n+1} = \left( \frac{h}{\sqrt{1-h^2}} + \frac{\bar{k}_1 \rho^2}{\sqrt{(1-h^2)^3}} \right) \omega_n. \end{cases}$$

Then, for  $\lambda > n+1$ , by (3. 14) and (3. 9) we have

$$\begin{aligned}
\omega_{a\lambda} &= (De_a, e_\lambda) = (d\bar{e}_a, \bar{\xi}_{\lambda-n+1}) = 0 \text{ for } 1 \leq a \leq n-1, \\
\omega_{n\lambda} &= (De_n, e_\lambda) = (de_n, \bar{\xi}_{\lambda-n+1}) \\
&= \frac{1}{\sqrt{1-h^2}} (d(-f\bar{e}_n + \rho\bar{\xi}_1), \bar{\xi}_{\lambda-n+1}) \\
&= \frac{\rho}{\sqrt{1-h^2}} \left( \frac{d\bar{\xi}_1}{ds}, \bar{\xi}_{\lambda-n+1} \right) d\bar{s} = \frac{\rho}{\sqrt{1-h^2}} \cdot \frac{h}{f} \bar{k}_{\lambda-n+1} \cdot \frac{\rho}{\sqrt{1-h^2}} \omega_n \\
&= \frac{h\rho^2}{f(1-h^2)} \bar{k}_{\lambda-n+1} \omega_n,
\end{aligned}$$

i. e.

$$(3.16) \quad \begin{cases} \omega_{a\lambda} = 0, & a = 1, 2, \dots, n-1; \\ \omega_{n\lambda} = \frac{h\rho^2}{f(1-h^2)} \bar{k}_{\lambda-n+1} \omega_n. \end{cases}$$

Now we state the definition of principal normal vectors for a submanifold introduced by the author in [5]. In general, let  $M$  be a submanifold of a Riemannian manifold  $\bar{M}$ . A normal vector  $v$  at a point  $x \in M$  is called a *principal normal vector* of  $M$  at  $x$ , if it satisfies the following condition:

There exists a tangent vector  $u \in M_x$ ,  $u \neq 0$ , such that

$$T_u z = (u, z) v \quad \text{for all } z \in M_x,$$

where  $M_x$  denotes the tangent space of  $M$  at  $x$  and  $T$  is the shape operator of  $M$  in  $\bar{M}$ .  $u$  is called a *principal tangent vector* for  $v$ .

It is evident that all the principal tangent vectors for  $v$  and the zero vector span a linear tangent subspace, which we denote by  $E(x, v)$ .

A  $C^\infty$  normal vector field  $V$  of  $M$  is called a *regular principal normal vector field*, if  $V$  is a principal normal vector at each point  $x$  of  $M$  and  $\dim E(x, V(x))$  is constant. When  $\bar{M}$  is of constant curvature,  $E(M, V) = \cup_x E(x, V(x))$  is a complete distribution of  $M$  (Theorem 1, [5]).

Now, going back to the previous situation, by means of (3.15) and (3.16), the shape operator of  $M^n(C)$  as a submanifold of  $S^{n+m-1}$  can be written as follows: For any tangent vectors  $X = \sum_i X_i e_i$ ,  $Z = \sum_i Z_i e_i$ ,

$$\begin{aligned}
(3.17) \quad T_x Z &= \left\{ \frac{h}{\sqrt{1-h^2}} \sum_{a=1}^{n-1} X_a Z_a + \left( \frac{h}{\sqrt{1-h^2}} + \frac{\bar{k}_1 \rho^2}{\sqrt{(1-h^2)^3}} \right) X_n Z_n \right\} e_{n+1} \\
&\quad + \frac{h\rho^2 X_n Z_n}{f(1-h^2)} \sum_{\lambda > n+1} \bar{k}_{\lambda-n+1} e_\lambda.
\end{aligned}$$

The formula (3. 17) implies immediately the following

**Theorem 2.**  $M = M^n(C)$  has two regular principal normal vector fields  $V$  and  $W$  given by

$$V = \frac{h}{\sqrt{1-h^2}} e_{n+1},$$

$$W = \left( \frac{h}{\sqrt{1-h^2}} + \frac{k_1 \rho^2}{\sqrt{(1-h^2)^3}} \right) e_{n+1} + \frac{h \rho^2}{f(1-h^2)} \sum_{\lambda > n+1} \bar{k}_{\lambda-n+1} e_\lambda,$$

if the tangent lines of  $C$  do not pass through the origin of  $D^m$ . Then  $E(M, V)$  and  $E(M, W)$  are distributions of dimension  $n-1$  and 1, respectively and

$$E(M, V) \oplus E(M, W) = T(M).$$

On the distributions in a sphere as  $V$  and  $W$ , we have the following theorem (Theorem 6, [6]):

**Theorem 3.** Let  $M^n (n \geq 3)$  be a minimal submanifold of  $S^{n+p} \subset R^{n+p+1}$  with two regular principal normal vector fields  $V$  and  $W$  such that

$$E(M^n, V) \oplus E(M^n, W) = T(M^n).$$

Then, there exists an  $(n+2)$ -dimensional subspace  $E^{n+2}$  of  $R^{n+p+1}$  through the origin such that

$$M^n \subset E^{n+2} \cap S^{n+p}.$$

**Theorem 4.**  $M^n(C)$  is minimal in  $S^{n+m-1}$  if and only if  $C$  is a geodesic of  $O_n^m$ .

*Proof.* By Theorem 2,  $M^n(C)$  has two regular principal normal vector fields  $V$  and  $W$  satisfying the condition as in Theorem 3.

If  $M^n(C)$  is minimal in  $S^{n+m-1}$ , by Theorem 3 there exists an  $(n+2)$ -dimensional linear subspace  $E^{n+2}$  of  $R^{n+m}$  through the origin such that

$$M^n(C) \subset E^{n+2} \cap S^{n+m-1}.$$

Hence, by the way of construction of  $M^n(C)$ ,  $C$  must lie in a plane through the origin. Accordingly, by (3. 1), (3. 2) and (3. 5) we have

$$(3. 18) \quad \bar{k}_3 = \bar{k}_4 = \cdots = \bar{k}_m = 0.$$

Thus, the condition that  $M^n(C)$  is minimal becomes

$$(3.19) \quad \frac{nh}{\sqrt{1-h^2}} + \frac{\rho^2 \bar{k}_1}{\sqrt{(1-h^2)^3}} = 0$$

by means of (3.17). Hence, by a result in [4],  $C$  is a geodesic of  $O_n^2$ . By means of Corollary of Theorem 1,  $C$  is also a geodesic of  $O_n^m$ .

Conversely, if  $C$  is a geodesic of  $O_n^m$ , then it lies in a plane through the origin. Thus, (3.18) is true for  $C$ . By means of (3.17),  $M^n(C)$  is minimal if (3.19) is true. Using the direction angle  $t$  of  $C$  in the plane, we have

$$\bar{k}_1 = -1 / \left( h + \frac{d^2 h}{dt^2} \right) \quad \text{and} \quad f = \frac{dh}{dt}.$$

Therefore, (3.19) can be written as

$$(3.20) \quad nh(1-h^2) \frac{d^2 h}{dt^2} + \left( \frac{dh}{dt} \right)^2 + (1-h^2)(nh^2 - 1) = 0.$$

This is also a condition that  $C$  is a geodesic of  $O_n^2$  (Proposition 1, [8]). Hence  $M^n(C)$  must be minimal in  $S^{n+m-1}$ . Q. E. D.

**Remark.** In order to prove Theorem 4, we can use Lemma 2. But, we have to take care of the following fact. If  $M^n(C_0)$  is minimal, we may consider  $C_0$  is a smooth arc in  $D^m$  and it is extremal with respect to the  $n$ -dimensional volume of the family of  $M^n(C)$  such that  $C$  are smooth curves in  $D^m$  with the same end points of  $C_0$ .

Finally, we shall give a remark on the representation of  $O_n^m$  like the Poincaré one of  $H^2 = O_0^2$ .

Let us suppose that  $n$  is any real number and denote the line element (1.2) of  $O_n^m$  by

$$(3.21) \quad ds_n^2 = (1 - (u, u))^{n-2} [(1 - (u, u))(du, du) + (u, du)^2].$$

In  $D^m$  we take the change of coordinate system:  $u = (u_1, \dots, u_m) \longrightarrow x = (x_1, \dots, x_m)$  given by

$$(3.22) \quad u = \frac{2x}{1+r^2}, \quad r = \sqrt{(x, x)}.$$

Then, we have

$$1 - (u, u) = \left( \frac{1-r^2}{1+r^2} \right)^2$$

$$\begin{aligned}(du, du) &= \frac{4}{(1+r^2)^4} \{(1+r^2)^2(dx, dx) - 4(x, dx)^2\}, \\(u, du) &= \frac{4(1-r^2)}{(1+r^2)^3} (x, dx).\end{aligned}$$

Substituting these into (3.21), we obtain

$$ds_n^2 = \frac{4(1-r^2)^{2(n-1)}}{(1+r^2)^{2n}} (dx, dx),$$

i. e.

$$(3.23) \quad ds_n^2 = \frac{4(1 - \sum_i x_i x_i)^{2(n-1)}}{(1 + \sum_i x_i x_i)^{2n}} \sum_j dx_j dx_j.$$

Especially, we have

$$(3.24) \quad ds_0^2 = \frac{4}{(1 - \sum_i x_i x_i)^2} \sum_i dx_i dx_i,$$

which is the Poincaré representation of the hyperbolic plane of curvature  $-1$ . Hence, we have from (3.23) and (3.24)

$$ds_n^2 = \left( \frac{1 - \sum_i x_i x_i}{1 + \sum_i x_i x_i} \right)^{2n} ds_0^2.$$

Therefore, we may call the expression (3.24) the Poincaré representation of  $O_n''$ .

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